

Key Setup Parameters for Meaningful Vibration Data Analysis

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Meaningful Vibration Data Analysis

- Lots of tools and techniques available.
- Sometimes can be a bit intimidating and burdensome.
- Need to take away some of the mystery.
- Make the best of the situation.
- Examine scientific terminology and industry jargon.

Getting Down to Basics

- Vibration is a leading indicator of machinery health.
- Accelerometer is like a doctor's stethoscope.
- Capture the raw data.
- Convert to a "signature" for comparison.
- Know the equipment make-up.
- Watch for patterns, amplitudes, and changes over time.

(Interpret information relative to PF curve)

Predictive Maintenance (PdM)

(an evolution from Breakdown to Preventive)

- 4 Key Elements to the process:
 - Detection
 - Analysis
 - Correction
 - Verification
- *Pinpoint a problem, get to the root cause, take action, and verify effectiveness.*

DETECTION

- Capture details on equipment and application.
- Choose the right sensor.
- *Set up the right measurement parameters.*
- Obtain good, solid data – also, repeatable.

ANALYSIS

- Examine trends, changes, patterns, and amplitudes. (*The “Signature”.*)
- Compare to known acceptable standards or baselines.

(Note: *Signature, Spectrum, and FFT (Fast Fourier Transform) are used synonymously.*)

CORRECTION

- Take actions against offending vibration levels:
 - ✓ Balancing.
 - ✓ Alignment.
 - ✓ Replacing defective bearings.
 - ✓ Tying down loose components.
 - ✓ Avoiding resonance.

The BIG 5!

VERIFICATION

- Perform a “Before and After” assessment.
- *Did the follow-up action make the situation better?*
- If the problem has been addressed, set a new measurement baseline for the future.

Primary Goals of the PdM Program

- Ensure convenient rework.
- Avoid panic.
- Avoid secondary damage.
- Promote safety.
- Reduce repair time.
- *Avoid any unnecessary downtime.*

12 Steps for Success

- **Survey the plant** in terms of critical, essential, balance of plant categories.
- **Choose the machines** to put into the program.
- **Optimize measurements** in terms of parameters and timing.
- **Choose the method** and **educate participants**.
- **Set criteria** (alarms) for assessment.
- **Baseline** the machine under consideration.
- thru 10, Setup, Measure, Store, Present (**detection**).
- Problem assessment (**analysis**).
- Correct the fault (**correction**).

(After step 12, the process can be re-entered at step 6.)

Establishing the Program

- Put equipment into categories of “critical”, “essential”, and “balance of plant”.
- Start with the critical machinery.
- Get into the physical make-up of the equipment and the application.
- Decide the kinds of measurements and sensors to be used.
- Look for vibration presence, patterns, and severity.

Vibration measurement

- Choose the best location.
- Choose the proper sensor.
- Make the proper placement – firm mounting and direction. (similar to sensitive directional microphone).
- Measure in several axes.
- *Set measurement parameters to get “tell-tale” data.*
- Set alarm limits for proper assessment. (typically “warning”, “alert”, and “danger”).

Other Key Considerations ...

- Know the make-up of the machine in terms of bearings, gearbox, pulleys, couplings, cooling fans (# of blades) and pumps (# of impellor blades).
- Know the 1X (i.e., running speed) of the machine being measured.
- Know the relative phase readings on key positions of the machine. (*This will show relative motion.*)

Key Measurement Parameters

- Time or frequency data to be captured.
- Sample time.
- Number of samples.
- Number of averages.
- Frequency range.
- Frequency resolution.

Data Interpretation

- Examining presence, patterns, and severity will lead to correction.
- There are typically 5 main causes for the vibration:
 - Unbalance.
 - Misalignment.
 - Bearing defects.
 - Looseness.
 - Resonance.

Getting Good Data

- Avoid the GIGO (garbage in, garbage out) principle.
- Make certain to have a good sensor, cabling, and connections.
- Ensure proper (solid) mounting (no rocking).
- Set up instrument parameters to get the right measurements.
- Make sure that the equipment is running.
- Be sure that it is the right location.
- Recognize “bad” data before moving on.
- Utilize auxiliary tools available to build confidence in the assessment. (*Examples here include bump tests, coastdown, cross-channel phase, and demodulation.*)

Measurement Considerations

- Right place, right time.
- Minimize outside influences.
- Time or frequency?
- Frequency band, F_{min} and F_{max} .
- Resolution.
- Windowing.
- Sampling time.
- Number of samples.
- Number of averages
- Accompanying speed and phase information?
- Additional simultaneous channel?

Measurement Relationships

- Highest frequency (Fmax)

$$F_{\max} \text{ (Hz)} = \# \text{ of samples} / (2.56 * \text{sample time})$$

(corollary: sample time = # lines of resolution / Fmax (Hz))

- Lines of resolution

$$\# \text{ Lines} = \text{samples} / 2.56$$

(corollary: samples = 2.56 * # lines)

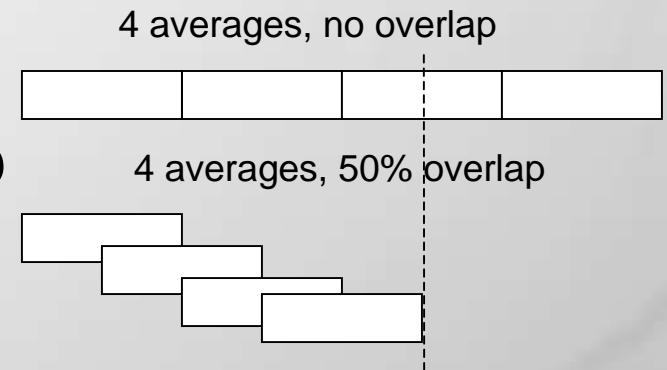
- Time for collection

$$\text{Time} = (\# \text{ averages} * \# \text{ lines}) / F_{\max} \text{ (in Hz)}$$

- Frequency resolution

$$\text{Resolution} = F_{\max} / \# \text{ lines}$$

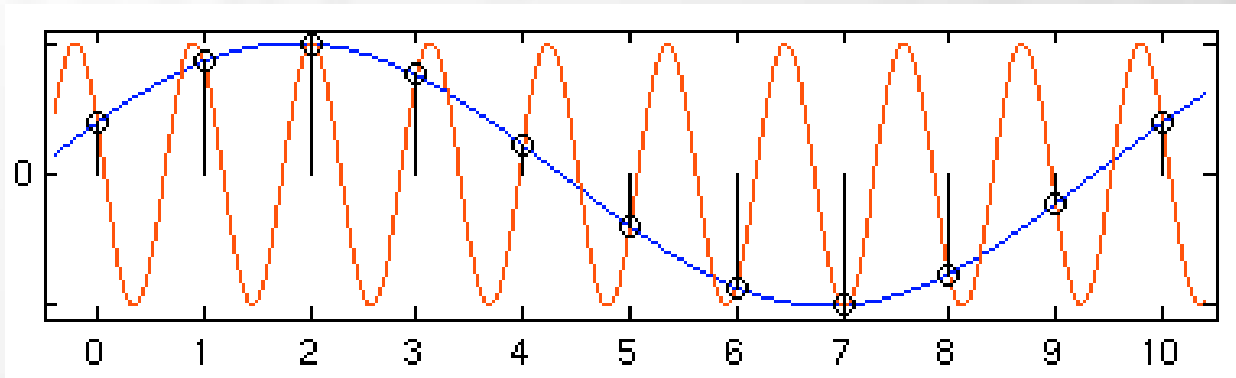
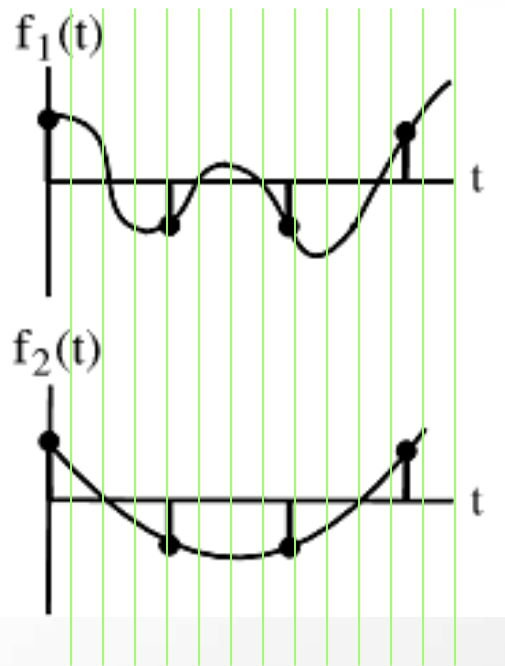
(Keep in mind the specifications for the sensor and instrumentation.)



Measurement Considerations

- Shannon (Nyquist) Sampling Theorem: Sampled signal can be completely reproduced if sampling frequency is at least twice the highest frequency content. (We use the factor 2.56 in digitizing.)
- Any attempt to do less results in “aliasing”.
- There is an inverse relationship between time sample and highest frequency content.
- More samples, less time results in higher frequency.

Digital Sampling... Example



Two very different signals with same sampling.

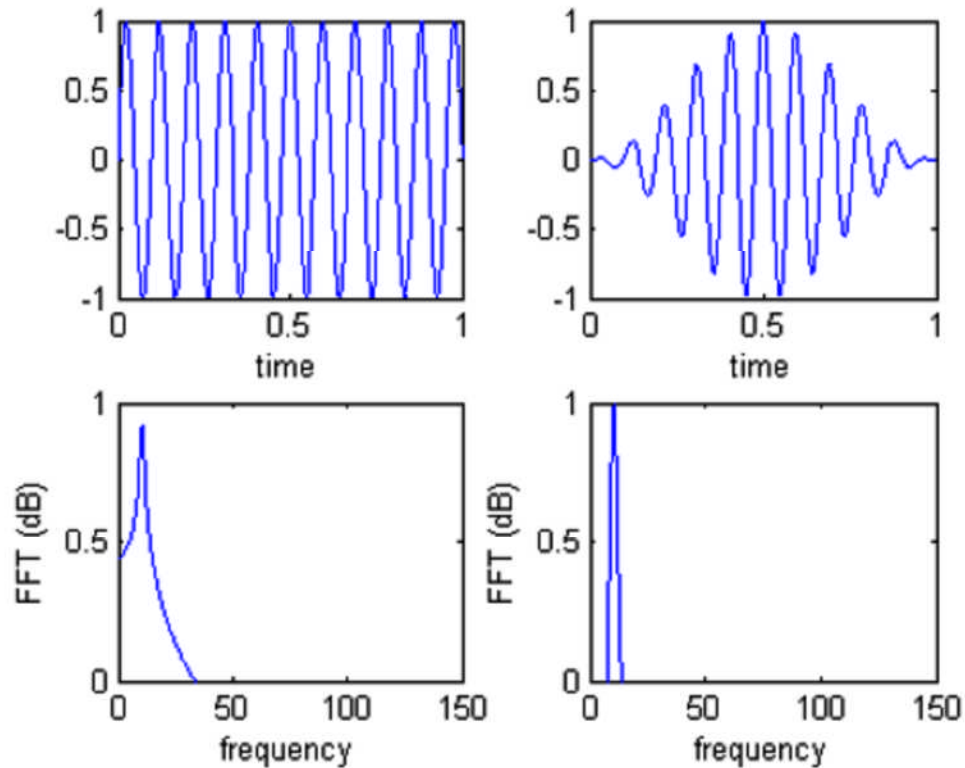
The more samples, the better reconstruction.

2.56X is a nice sampling factor in digitizing.

Further considerations

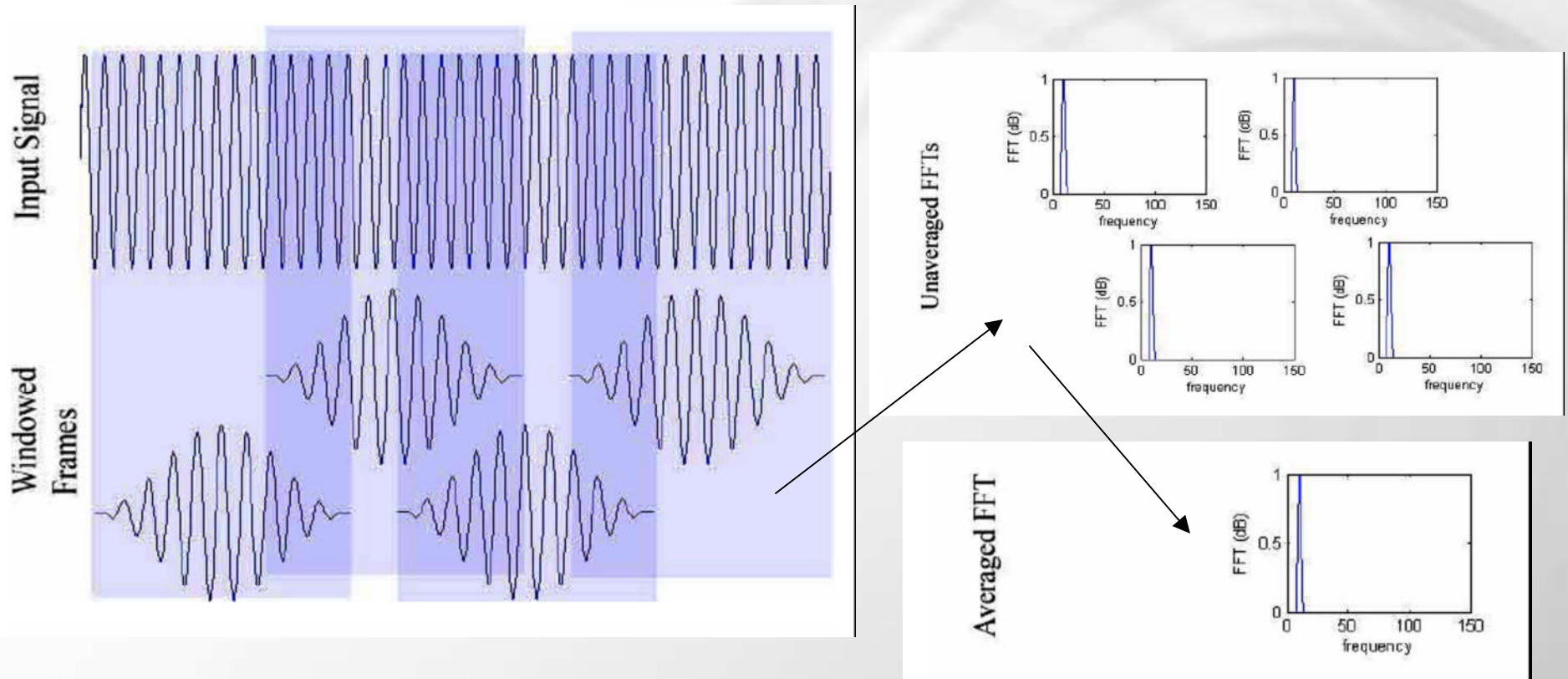
- Product(s) specifications and limitations.
- Measurement capture.
- Measurement processing.
- Measurement unit (acceleration, velocity, displacement).
- Measurement scaling (rms, average, peak, pk-pk).

Windowing for sampling



Comparison of non-periodic sine wave and FFT with leakage (left) to windowed sine wave and FFT showing no leakage (right).

Overlapping Averages



Overlap processing shortens the acquisition time by recovering a portion of each previous frame that otherwise is lost due to the effect of the FFT window,

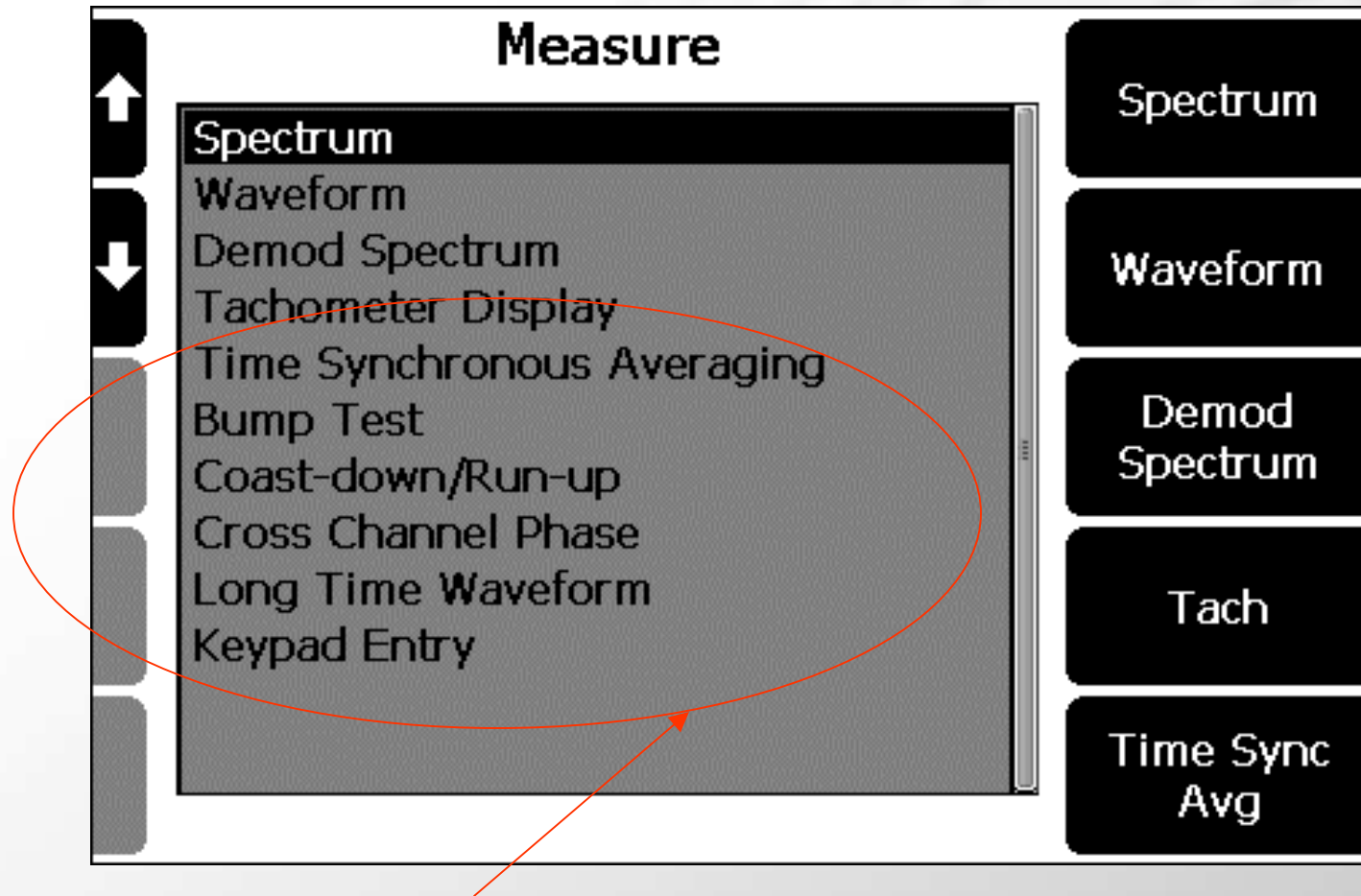
Example – at instrument side

Sensor		
Name	Accel 100mV/g	100
Type	Accel.	mV/g
Voltage Rng and Coupling	AC +/- 8V	
Settling	3 s	ON
Auto Settling	ON	CHECK

Key settings to address

Example – at instrument side

Most commonly used
On routine data collection



Advanced analysis

FFT (Spectrum) Measurement

Typical Settings Menu

Spectrum		
<small>ALT</small> Number of Averages	4	Velocity
<small>ALT</small> Average Type	Linear	60 kCPM
<small>ALT</small> Average Overlap	50%	800
<small>ALT</small> Window	Hanning	60 CPM
<small>ALT</small> Sensor Setup	CH1: Accel 100mV/	OFF
		<small>ALT</small> Store Units
		<small>ALT</small> Fmax
		<small>ALT</small> Spectral Lines
		<small>ALT</small> Fmin
		<small>ALT</small> Tach Trigger

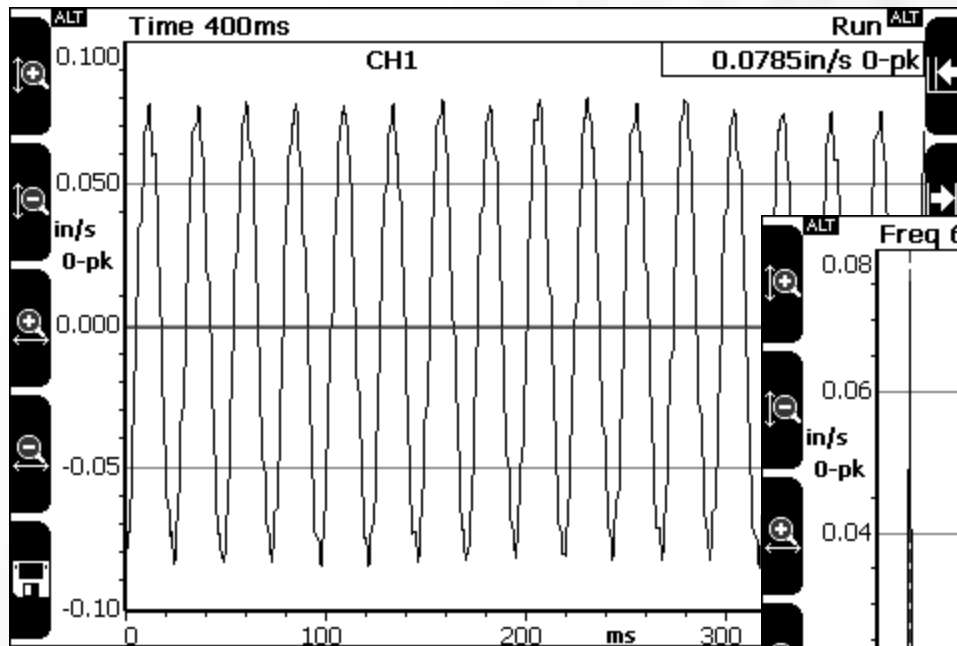
TWF (Time Waveform) Measurement

Typical Settings Menu

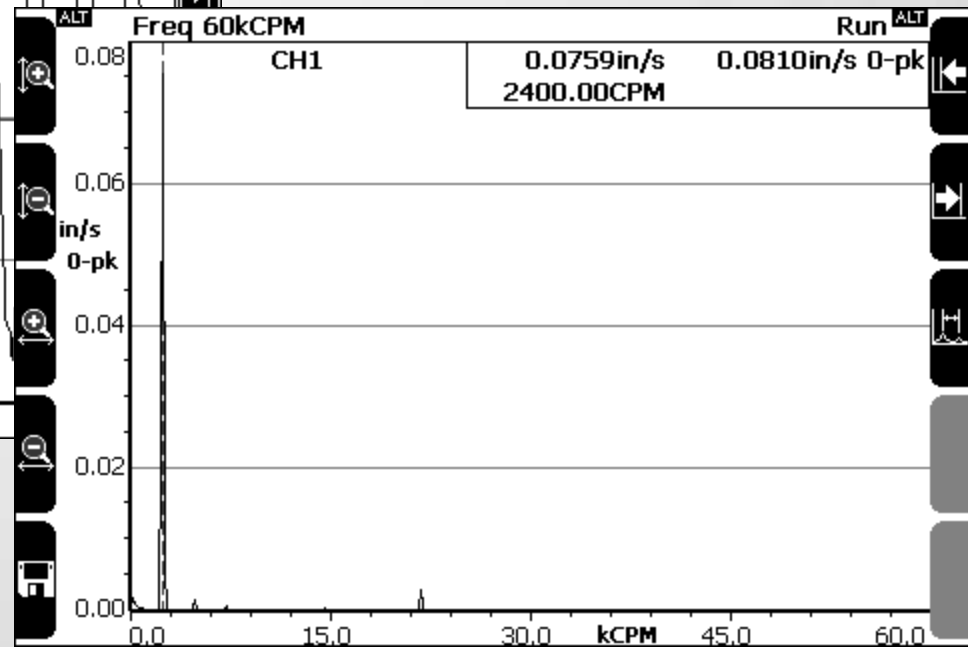
Waveform		
<small>ALT</small> Number of Averages	1	Velocity
<small>ALT</small> Average Type	Linear	60 kCPM
		1024
		400ms
<small>ALT</small> Sensor Setup	CH1: Accel 100mV/	OFF
		<small>ALT</small> Store Units
		<small>ALT</small> Equivalent Fmax
		<small>ALT</small> Number of Samples
		<small>ALT</small> Duration
		<small>ALT</small> Tach Trigger

Measurements at Instrument

Time Waveform

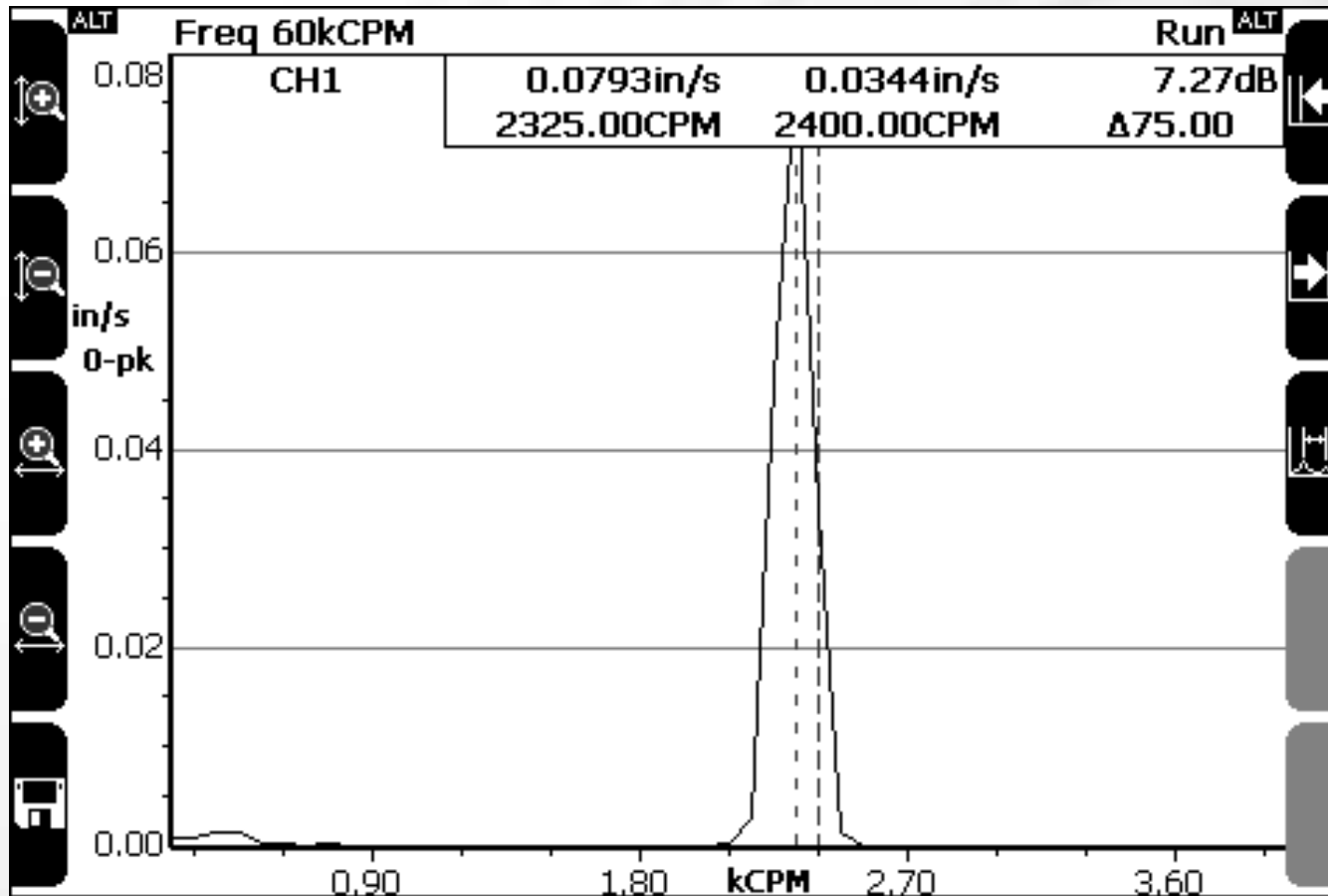


FFT



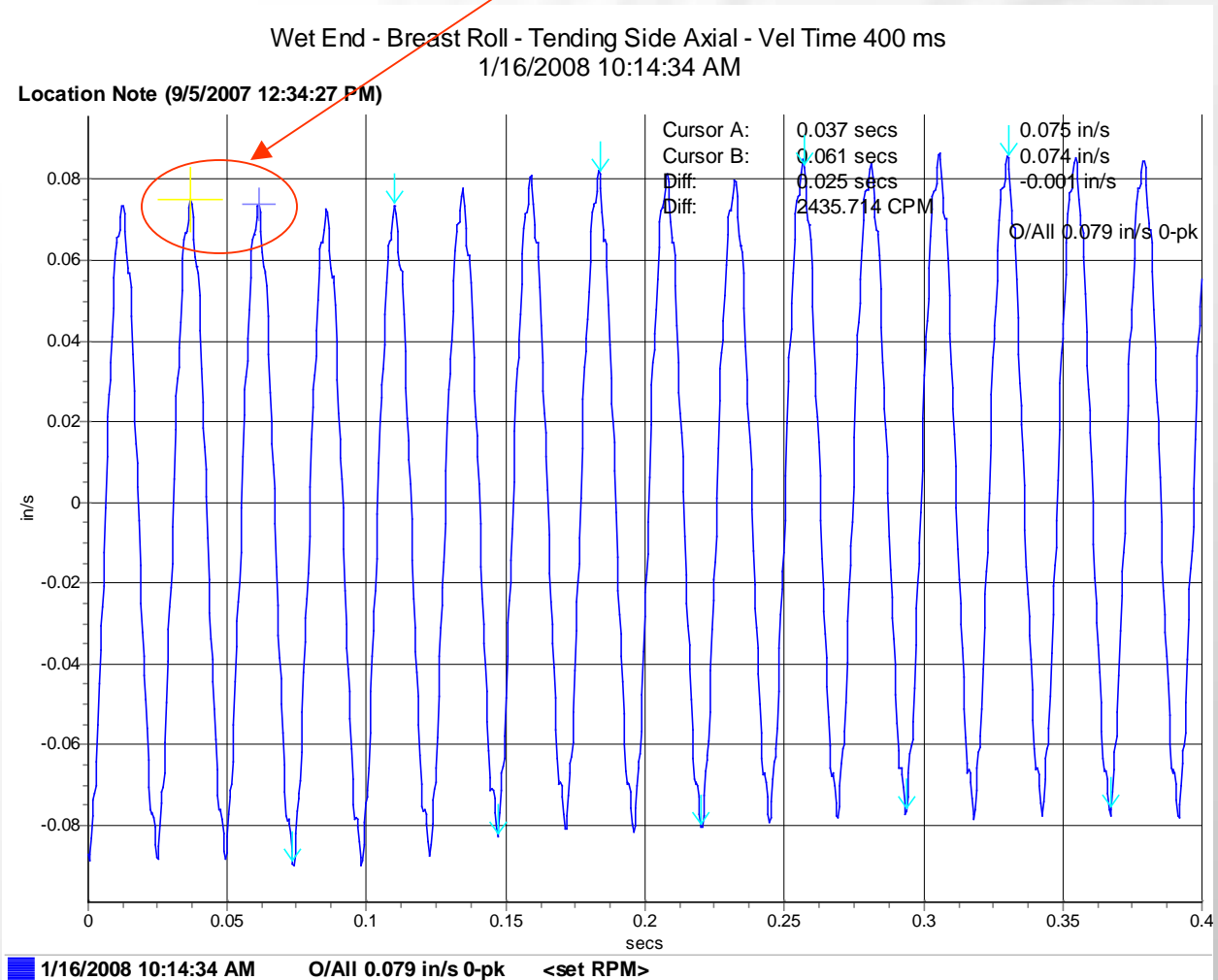
Zoomed FFT on Instrument

Shows more precise frequency and resolution



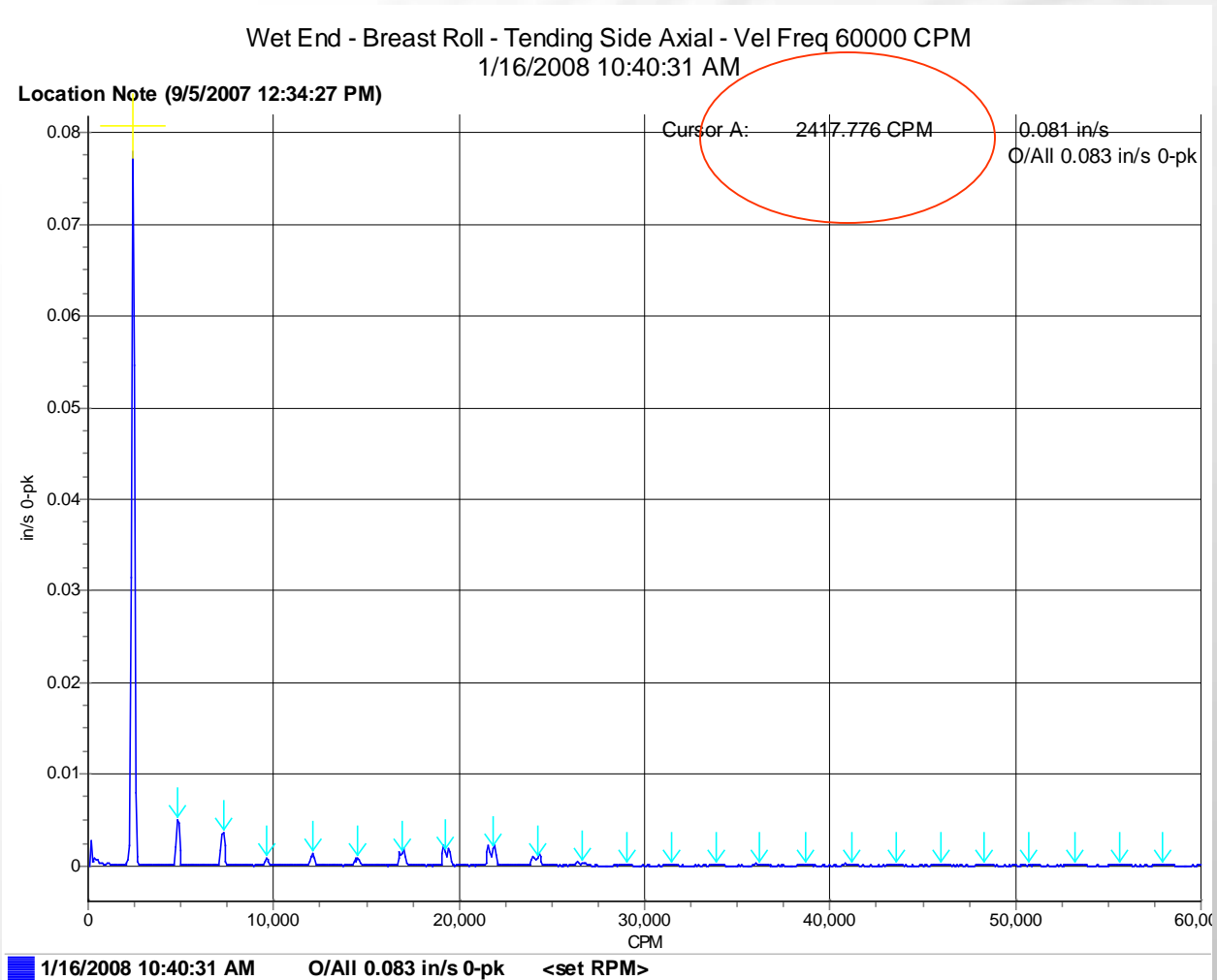
Viewed at PC

Note delta cursors to determine approximate frequency



Viewed at PC

Interpolated running frequency



Setup Parameters - TWF

Edit Paramset / Schedule Entry

Select Parameter Set: Vel Time 400 ms

Description:

Domain: Frequency Time Demodulation

Measurement Units: Velocity (in/s 0-pk)

Warning: These settings are not supported by all vb instruments. See the Applicable vb Instrument tab for details.

Read RPM from Tach
 Tach Triggered (time synchronous) Default RPM:
 Ask user for RPM when measurement is taken
 Record this schedule entry when performing a Route.

Parameters Channel/Sensor Applicable vb Instrument Baseline Overall RMS

Items marked with a * are not supported by all instruments:

Number of samples:
Duration: ms
Equivalent FMax:

Estimated Recording Time: 0.4 seconds

OK Cancel Help

Note the settings and calculated equivalent Fmax value and estimated time.

Setup Parameters - FFT

The screenshot shows a software dialog box titled "Edit Paramset / Schedule Entry". At the top, "Select Parameter Set" is set to "Vel Freq 60000 CPM". The "Domain" is set to "Frequency". "Measurement Units" are "Velocity (in/s 0-pk)". A warning message states: "Warning: These settings are not supported by all vb instruments. See the Applicable vb Instrument tab for details." Below this, there are checkboxes for "Read RPM from Tach" (checked), "Record Phase Data (requires Tach)", "Ask user for RPM when measurement is taken", and "Record this schedule entry when performing a Route". The "Default RPM" is set to 0. The "Parameters" tab is selected, showing "Fmin: 60 CPM", "Fmax: 60000 CPM", "Lines: 800", "Average type: Linear", and "Number of averages: 4". The "Estimated Recording Time" is 2 seconds. At the bottom are "OK", "Cancel", and "Help" buttons.

Select Parameter Set: Vel Freq 60000 CPM

Description:

Domain: Frequency Time Demodulation

Measurement Units: Velocity (in/s 0-pk)

Warning: These settings are not supported by all vb instruments. See the Applicable vb Instrument tab for details.

Read RPM from Tach
 Record Phase Data (requires Tach) Default RPM: 0
 Ask user for RPM when measurement is taken
 Record this schedule entry when performing a Route.

Parameters Channel/Sensor Applicable vb Instrument Baseline Overall RMS FFT Options

Items marked with a * are not supported by all instruments:

Fmin: 60 CPM
Fmax: 60000 CPM
Lines: 800

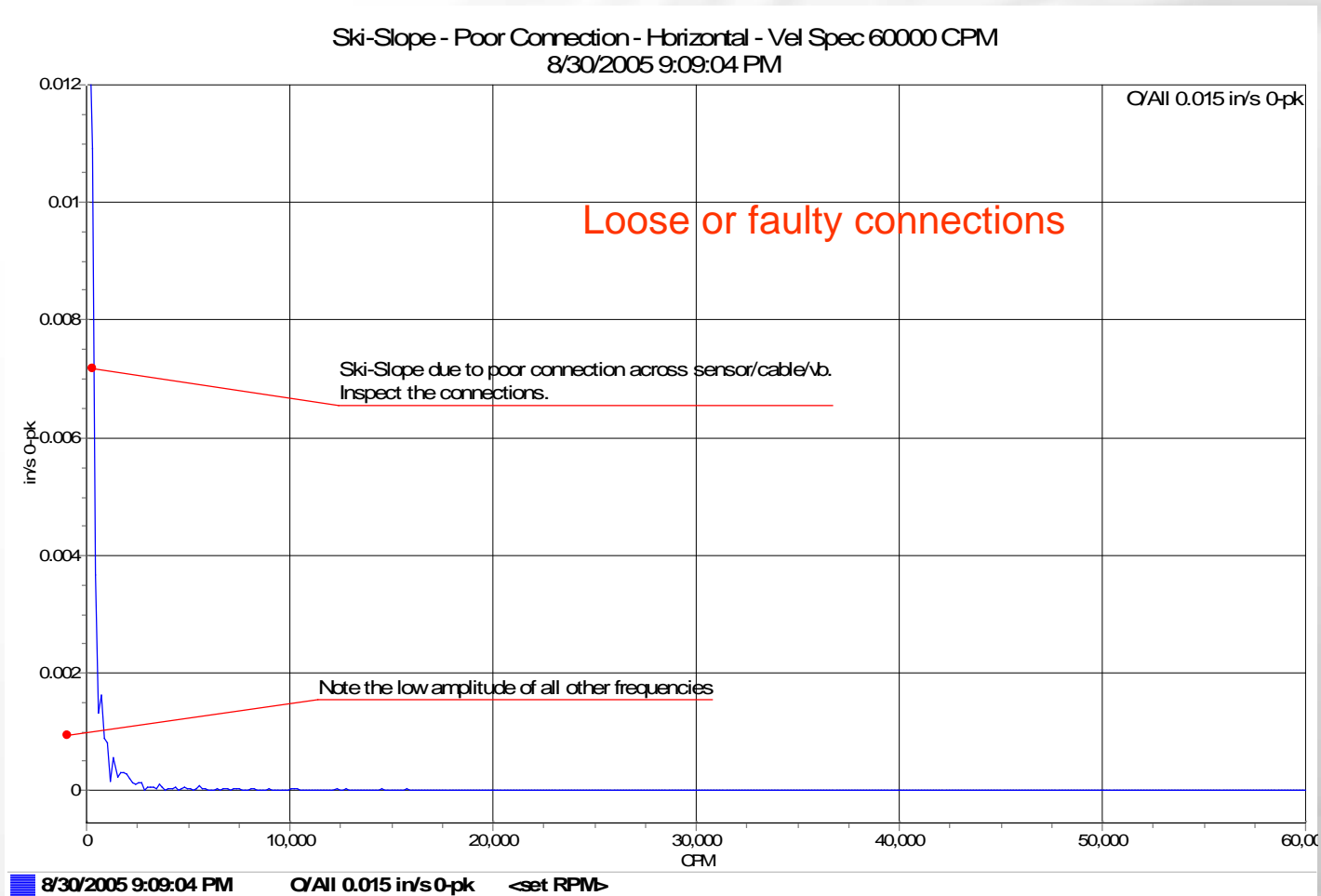
Average type: Linear
Number of averages: 4

Estimated Recording Time: 2 seconds

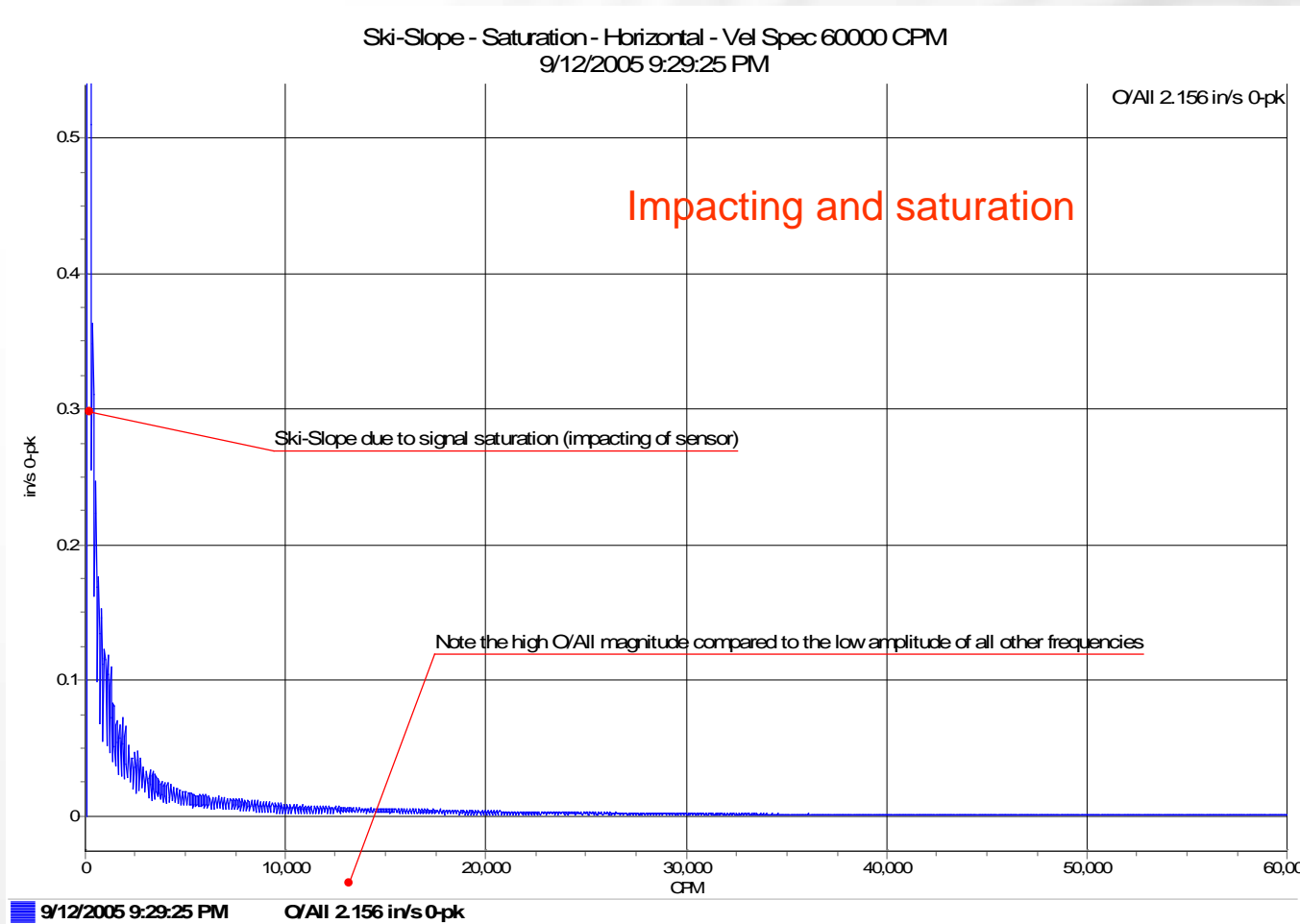
OK Cancel Help

Note the settings and estimated time.

Examples of Field Problems

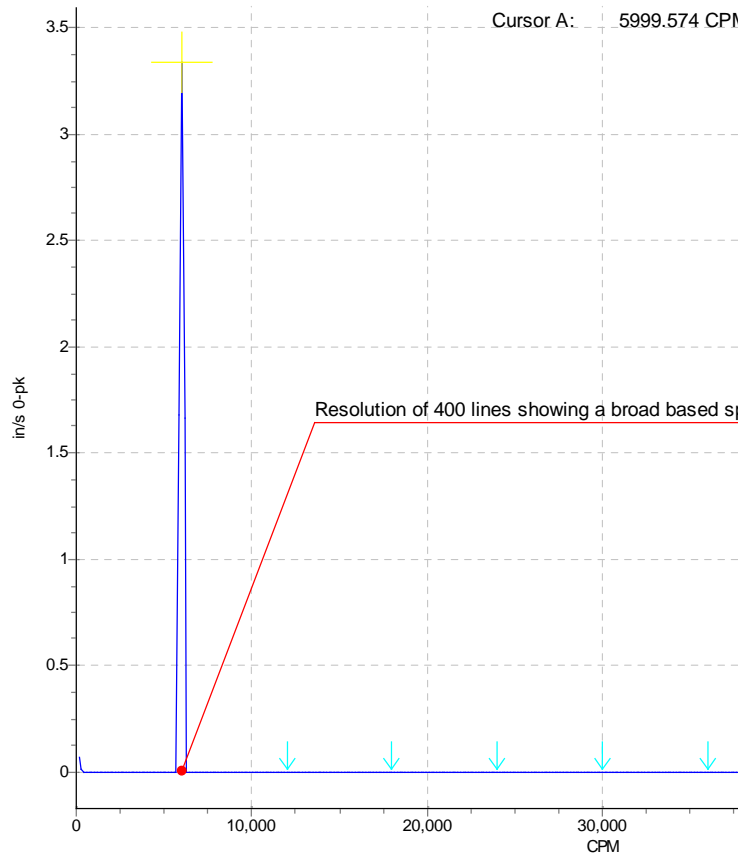


Examples of Field Problems



Example of Setup Issues

Resolution - Low - Horizontal - Vel Freq 60000 CPM
7/24/2005 6:31:06 PM



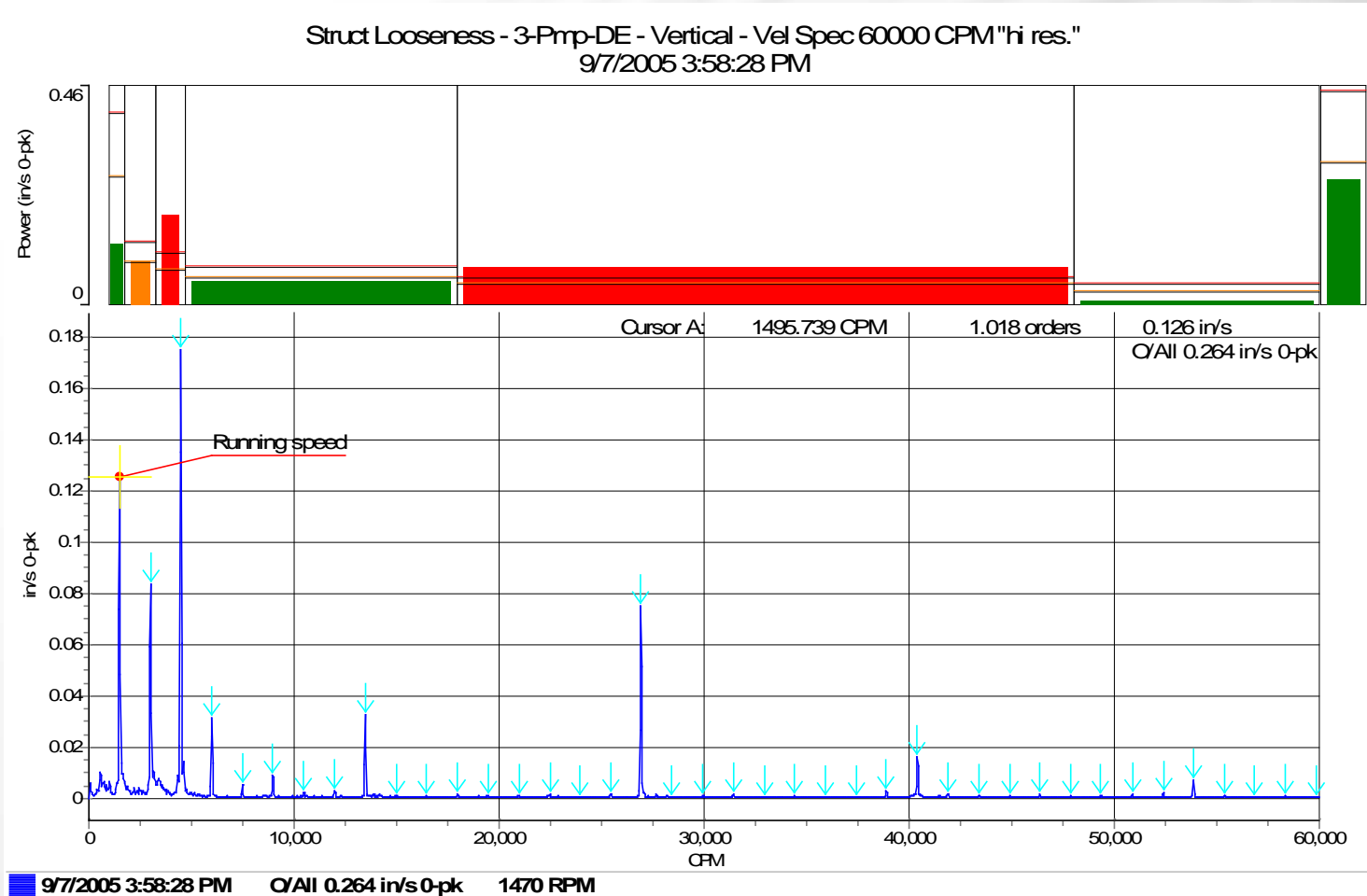
7/24/2005 6:31:06 PM O/All 3.34 in/s 0-pk 5999.574 RPM

Resolution - High - Horizontal - Vel Freq 60000 CPM
7/24/2005 6:31:17 PM



7/24/2005 6:31:17 PM O/All 3.339 in/s 0-pk <set RPM>

Example of Good Data for Analysis



Summary – Key Considerations

- Know the equipment and application.
- Recognize changing conditions.
- Choose the best shot at capturing the event.
- Choose the best sensor for the job.
- Choose the best location for the measurement.
- Make appropriate settings for the measurement.
- Capture good quality data.
- Transform data to information.
- Identify tell-tale signs of trouble.
- Decide a course of action.

Concluding Remarks

- Vibration is a primary measurement for an effective PdM program.
- Education and experience in the technology and techniques are essential for success.
- Get management 'buy-in' on the process.
- Know the equipment in terms of physical make-up and intended operation.
- Know standards for acceptable operation.
- Know the tell-tale signs for potential problems.
- Know the tools available for the program.
- Perform the proper setup for acquiring data.
- Be confident in assessing the situation.
- Have confidence in making the call for action.

Questions and/or Comments?

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